

Technical data:

Power supply:	24V DC Power consumption	Power supply 12 mA
Interface:	Universal Inputs/Outputs Inputs Input resolution RS-485	16 4 12bits 1
Clamps:	KNX/EIB Inputs/Outputs	1.5mm2 1.5mm2
Enclosure:	Material: Color: Dimensions:	Polyamide Gray 70(W)x91(H)x56(L) mm
Protection:	IP20 according to EN 60529	
Usage temperature:	-5C ... +55C	
Storage temperature:	-20C ... +70C	
Net weight:	104g	
Gross weight:	122g	



Caution

Security advice

The installation and assembly of electrical equipment may only be performed by skilled electrician. The devices must not be used in any relation with equipment that supports, directly or indirectly, human health or life or with application that can result danger of people, animals or real value

Mounting advice

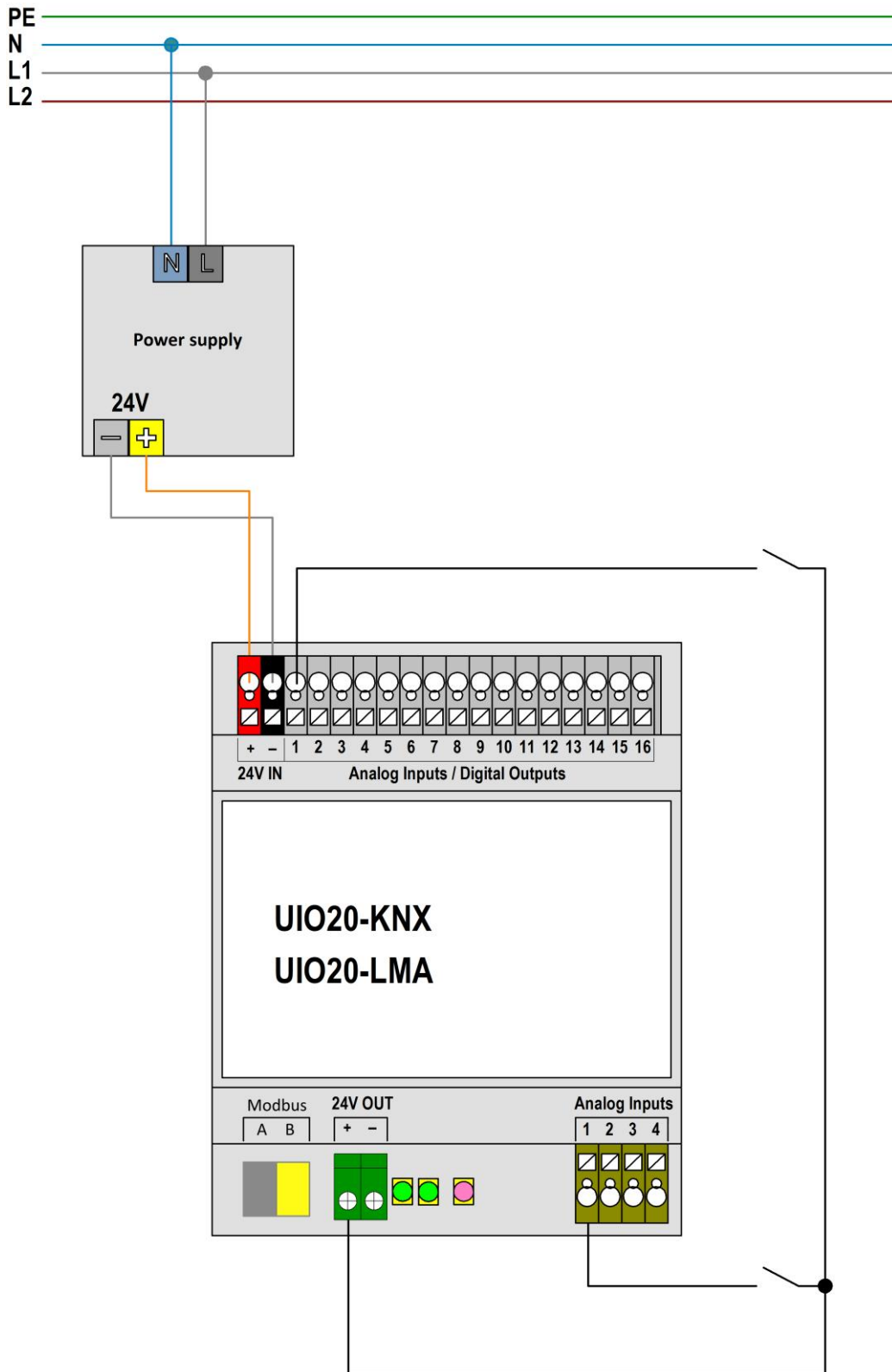
The devices are supplied in operational status. The cables connections included can be clamped to the housing if required.

Electrical connection

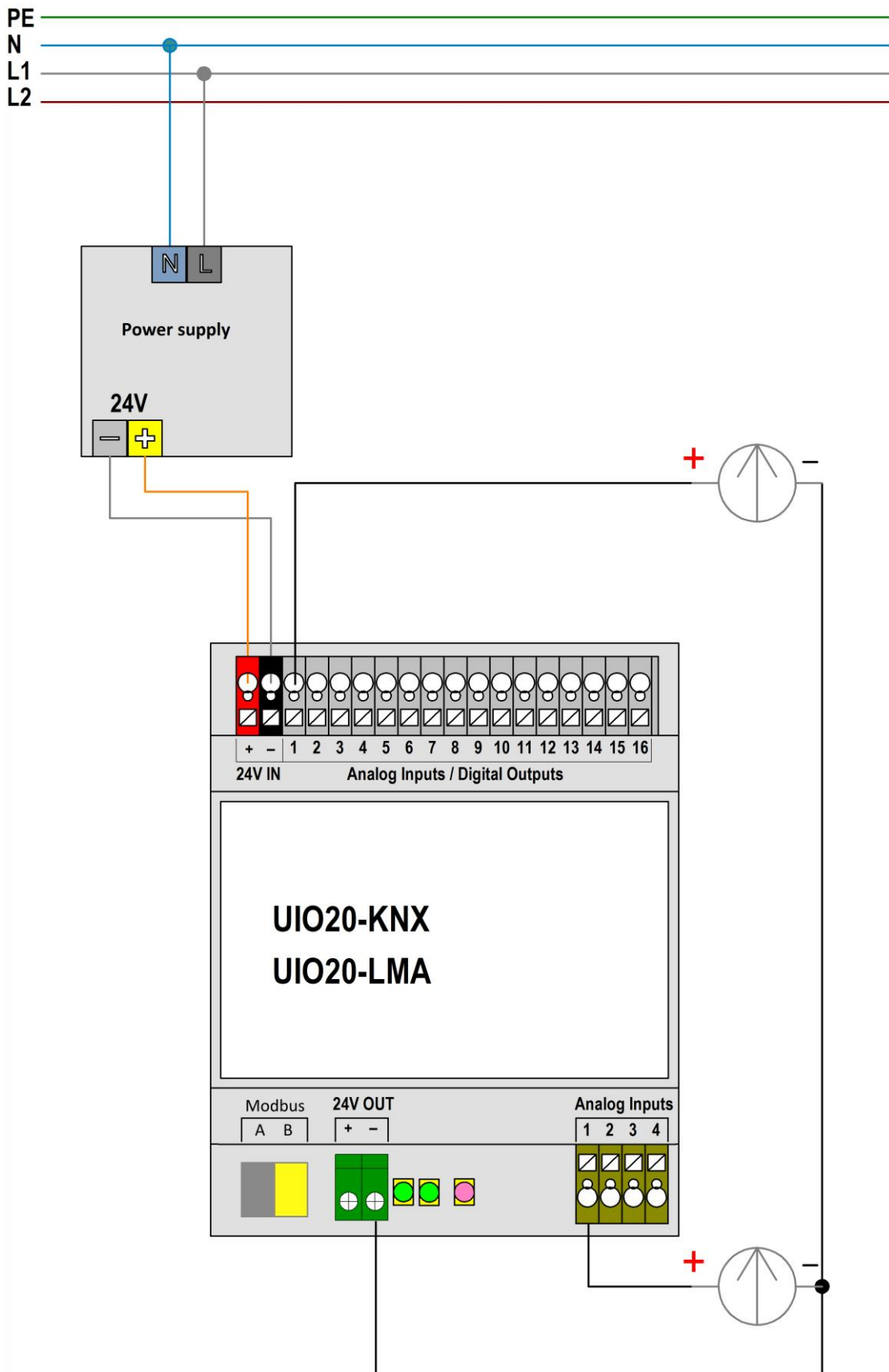
The devices are constructed for the operation of protective low voltage (SELV). Grounding of device not needed. When switching the power supply on or off, power surges must be avoided.

Push-button connection

We do not recommend to interconnect pushbuttons to Modbus device because of the polling – the commands will not be executed in real-time.



Voltage sensor connection

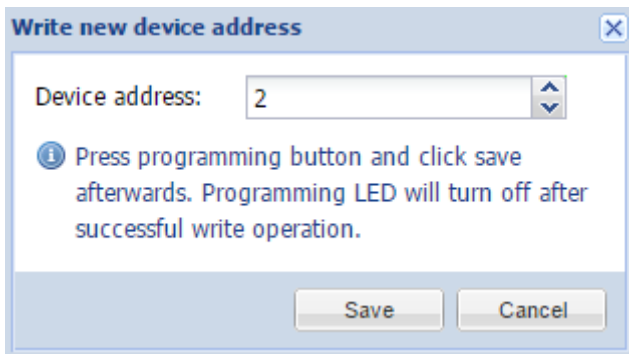


Default address

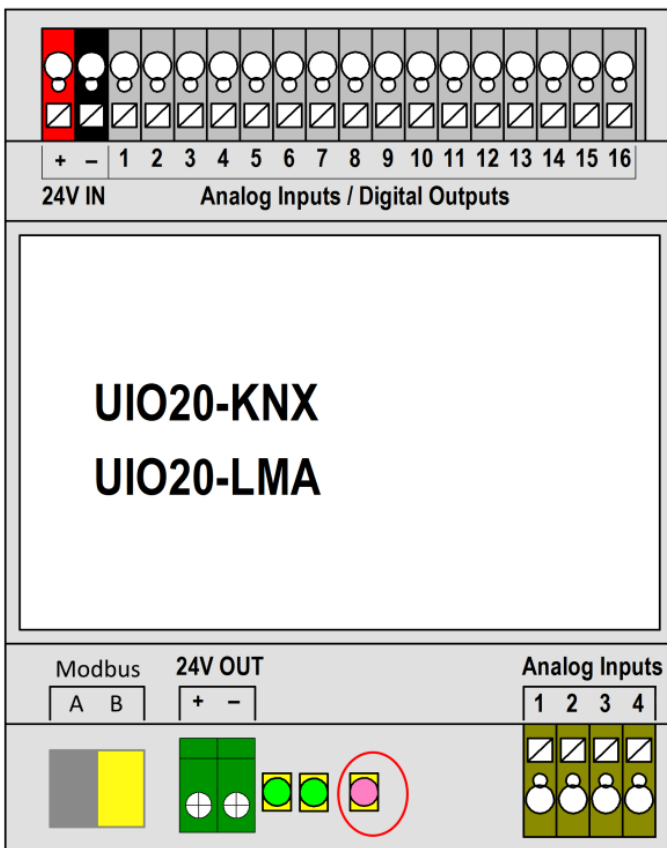
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Configuring UIO20 on LogicMachine

Program address for UIO20 Modbus device



There is a separate Write address button to program address for UIO20 device. Press programming button and click save afterwards. Programming LED will turn off after successful write operation.



UIO20 Modbus device profile

In LogicMachine Modbus devices are added as *.json profile files. You can download UIO20.json here:

<http://openrb.com/wp-content/uploads/2015/06/UIO20.json>

A fragment from UIO20 profile file:

```
{
  "manufacturer": "Embedded Systems",
  "description": "Universal 16+4 I/O module",
  "mapping": [
    { "name": "Output 1", "bus_datatype": "bool", "type": "coil", "address": 0, "writable": 1 },
    { "name": "Input 1", "bus_datatype": "float16", "type": "inputregister", "address": 0,
      "value_multiplier": 0.001, "units": "V" }
  ]
}
```

Name – Object name, e.g. Output 2 (String, Required)

Bus_datatype - KNX object data type, key from **dt** table, e.g. float32 (String/Number, Required)

Type – Modbus register type, possible values: **coil discreteinput register inputregister** (String, Required)

Address – Register address (0-based) (Number, Required)

Writable - Set to **true** to enable writing to register if **type** is either **coil** or **register** (Boolean)

Datatype – Modbus value data type. If set, conversion will be done automatically. Possible values: **uint16 int16 float16 uint32 int32 float32 uint64 int64 quad10k s10k** (String)

Value_delta – New value is sent when the difference between previously sent value and current value is larger than delta. Defaults to 0 (send after each read) (Number)

Value_multiplier – Multiply resulting value by the specified number, **value = value_base + value * value_multiplier** (Number)

Value_bitmask – Bit mask to apply, shifting is done automatically based on least significant 1 found in the mask (Number)

Value_nan – Array of 16-bit integers. If specified and read operation returns the same array no further processing of value is done (Array)

Value_conv – Apply one of built-in conversion functions (String, Internal)

Value_custom – Name of a built-in enumeration or a list of **key -> value** mapping, resulting value will be 0 if key is not found (String/Object)

Internal – Not visible to user when set to **true**, should be used for **scale** registers (Boolean)

Units – KNX object units/suffix (String)

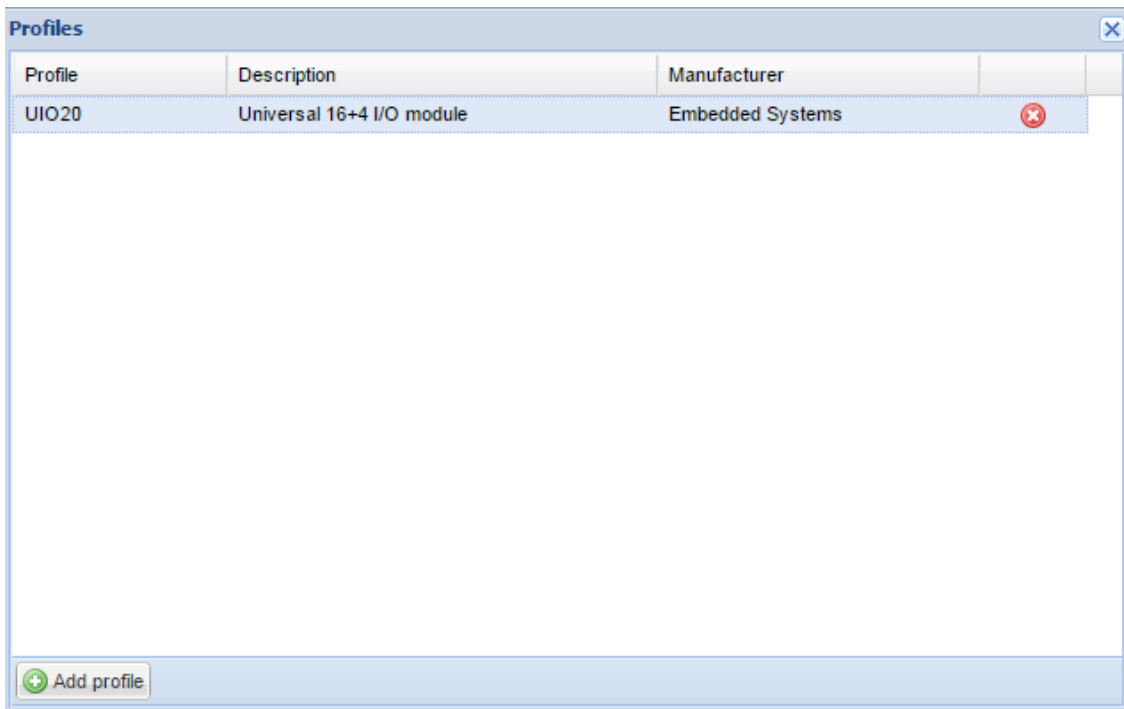
Address_scale – Address of register containing value scale, **value = value * 10 ^ scale** (Number)

Read_count – Number of register to read at once (for devices that only support reading of a specific block of registers) (Number)

Read_swap – Swap register order during conversion (endianness) (Boolean)

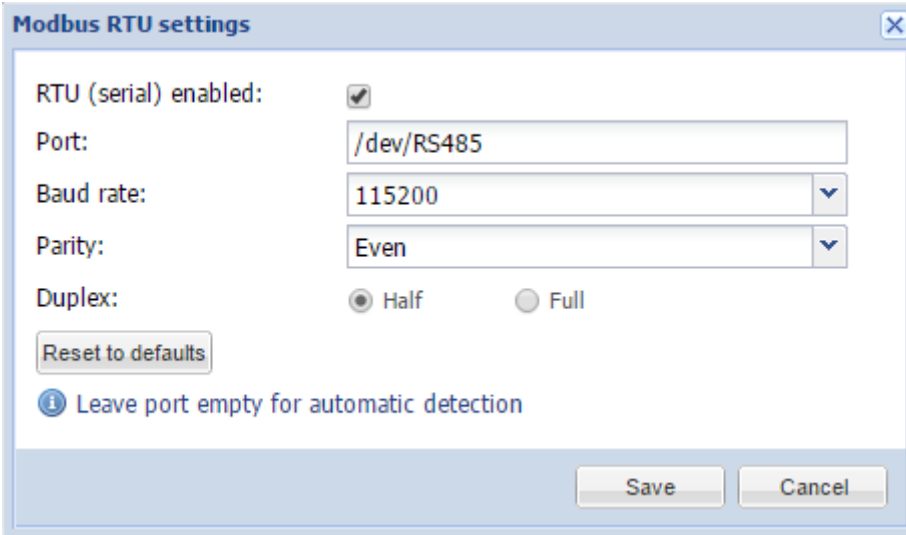
Read_offset – Position of first register of data from the block of registers (0-based) (Number)

When the Modbus device profile file is created, upload it by clicking on *Profiles* button.



Modbus RTU settings

If the communication is over Modbus RTU protocol (over RS-485 serial port), you should do base serial port settings by clicking on *RTU settings* button.



The image shows a dialog box titled "Modbus RTU settings". It contains the following fields and controls:

- RTU (serial) enabled:** A checked checkbox.
- Port:** A text input field containing "/dev/RS485".
- Baud rate:** A dropdown menu showing "115200".
- Parity:** A dropdown menu showing "Even".
- Duplex:** Two radio buttons, "Half" (selected) and "Full".
- Reset to defaults:** A button.
- Leave port empty for automatic detection:** A link with an information icon.
- Save** and **Cancel** buttons at the bottom right.

RTU (serial) enabled – define either RTU is enabled or not

Port – port name. In case of several RS-485 ports on the device, the name of the port is incremented by one, e.g. RS485-1, RS485-2, RS485-3 etc.

Baud rate – baud rate for the connection

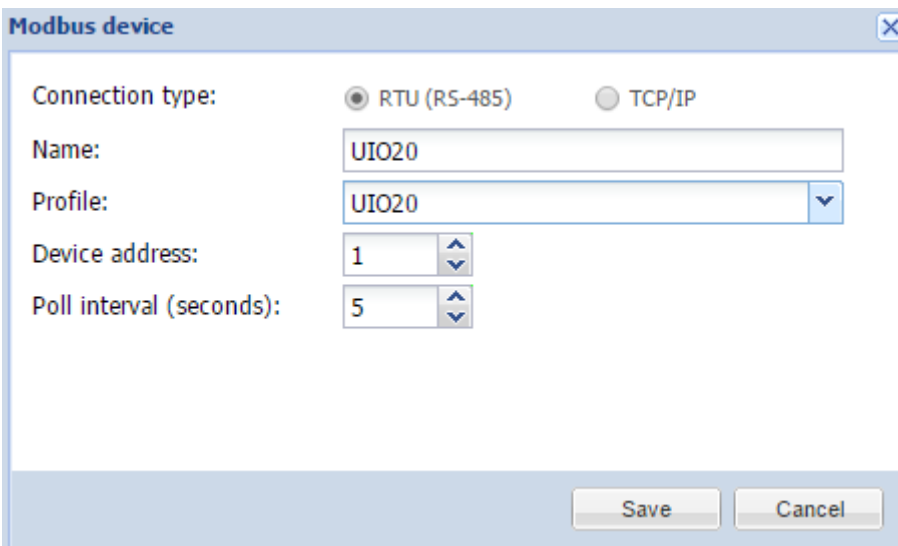
Parity – parity for the connection

Duplex – specify either it is *half* or *full* duplex

Reset to defaults – reset RTU settings to defaults

Adding Modbus device

Once profiles are defined and RTU settings set, add Modbus device by clicking *Add device* button.



The image shows a dialog box titled "Modbus device". It contains the following fields and controls:

- Connection type:** Two radio buttons, "RTU (RS-485)" (selected) and "TCP/IP".
- Name:** A text input field containing "UIO20".
- Profile:** A dropdown menu showing "UIO20".
- Device address:** A spinner box showing "1".
- Poll interval (seconds):** A spinner box showing "5".
- Save** and **Cancel** buttons at the bottom right.

Connection type – define either it is Modbus RTU or Modbus TCP connection

Name – name of the device


Profile – profile of the device

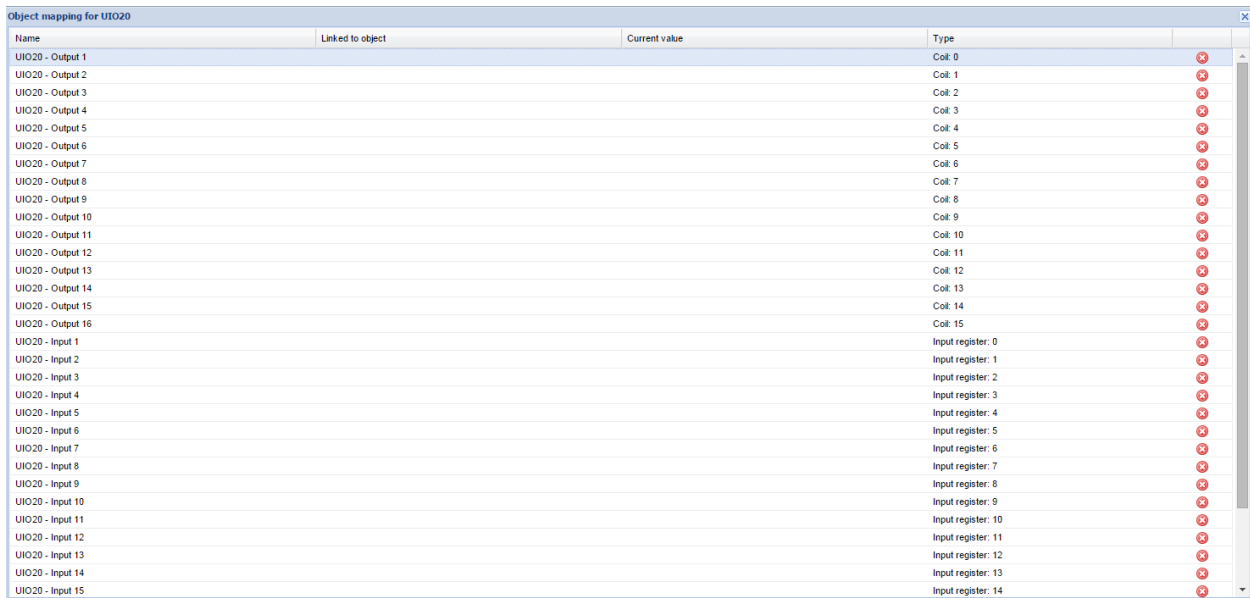
Device address – device address

Poll interval (seconds) – interval to poll the device

IP – IP address of the device in case Modbus TCP is used

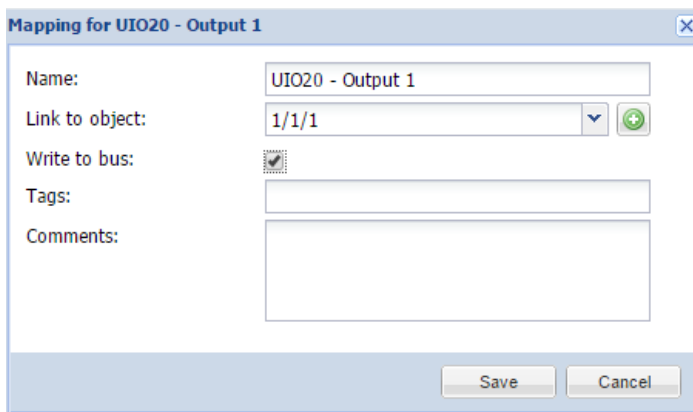
Port – Communication port of the device in case Modbus TCP is used

Once the device is added, you can do mapping to KNX addresses by clicking on  icon. First, you see a list of all objects on the Modbus device.



Name	Linked to object	Current value	Type
UIO20 - Output 1			Coil 0
UIO20 - Output 2			Coil 1
UIO20 - Output 3			Coil 2
UIO20 - Output 4			Coil 3
UIO20 - Output 5			Coil 4
UIO20 - Output 6			Coil 5
UIO20 - Output 7			Coil 6
UIO20 - Output 8			Coil 7
UIO20 - Output 9			Coil 8
UIO20 - Output 10			Coil 9
UIO20 - Output 11			Coil 10
UIO20 - Output 12			Coil 11
UIO20 - Output 13			Coil 12
UIO20 - Output 14			Coil 13
UIO20 - Output 15			Coil 14
UIO20 - Output 16			Coil 15
UIO20 - Input 1			Input register: 0
UIO20 - Input 2			Input register: 1
UIO20 - Input 3			Input register: 2
UIO20 - Input 4			Input register: 3
UIO20 - Input 5			Input register: 4
UIO20 - Input 6			Input register: 5
UIO20 - Input 7			Input register: 6
UIO20 - Input 8			Input register: 7
UIO20 - Input 9			Input register: 8
UIO20 - Input 10			Input register: 9
UIO20 - Input 11			Input register: 10
UIO20 - Input 12			Input register: 11
UIO20 - Input 13			Input register: 12
UIO20 - Input 14			Input register: 13
UIO20 - Input 15			Input register: 14

Click on specific object to do mapping.



Mapping for UIO20 - Output 1

Name: UIO20 - Output 1

Link to object: 1/1/1

Write to bus:

Tags:

Comments:

Save Cancel